#### X-88017/1/2016 NHP / 15 79-1634 Government of India Ministry of Jal Shakti Department of Water Resources, RD & GR National Hydrology Project

2<sup>nd</sup> Floor, Rear Wing, Mahanagar Doorsanchar Sadan 9, CGO Complex, Lodi Road, New Delhi-110003. Dated the 20<sup>th</sup> July, 2021

Dear Sirs,

As you are aware under National Hydrology Project (NHP), Survey of India (SoI) has developed two important tools for ascertaining positional accuracy in a precise manner with substantial reduction in time of observation and other related efforts. These tools are:-

- 1. Continuous Operating Reference Station (CORS) ie, active network of reference stations.
- 2. Geoid model

Whereas CORS system will provide the latitude and longitude of a station/point with accuracy in centimetres and height of station with respect to the ellipsoid datum, Geoid model will be used to convert the ellipsoidal heights into ortho-metric height (i.e. altitude above mean sea level.

CORS system has been established by the Survey of India in the States of Uttar Pradesh and Uttarakhand (under NHP) whereas the same has been established for Maharashtra, Karnataka and Haryana under non NHP. The system is nearing completion in Punjab, Rajasthan, and Madhya Pradesh.

Geoid model has completed by the Survey of India for Uttar Pradesh, West Bengal, Bihar, Jharkhand, Haryana and Uttarakhand (in the districts of Dehradun, Haridwar, Udham Singh Nagar, Pauri Garhwal and Tehri Garhwal). Geoid model for Punjab, Goa, Kerala and Himachal Pradesh would be completed shortly. Considering the utility of these systems for survey works associated with Water Resources as well as other engineering applications. SoP has been prepared by the Survey of India and the same is attached herewith along with the relevant annexures.

Since CORS network is not completed throughout the country, the SoP also includes procedure for using SOI Ground Control Points (GCPs) as reference stations i.e. passive network of stations.

Annexures have been prepared assuming that the user is acquainted with the GPS data processing knowledge and having basic survey skills using DGPS. However, it is felt that most of the users may not be having clear knowledge as above physical training needs to require acquiring requisite skill. As such, you are requested to identify suitable officers who can be imparted training by SOI for utilising these tools. The training period is expected to be of at least 3 working days and training would be carried out in SOI Complex at Dehradun. Convenient dates for training may also be communicated to SOI for the proposed training program so that Survey of India can arrange such trainings on mutually convenient dates.

Yours sincerely,

Encl: As above

(Rakesh Kashyap) Senior Joint Commissioner (NHP) Tel:- 011- 24367081

To:

Nodal Officers of All Implementing Agencies under NHP.

#### **Copy for information:**

- 1. PPS to JS (A, IC & GW), D/o WR, RD & GR, New Delhi
- 2. Project Director, Survey of India.
- 3. SJC I/SJC-II/ SJC-III/ DS , NHP, New Delhi
- 4. DC/ DD (NHP) New Delhi
- 5. DTL, TAMC, New Delhi

#### Annexure 'A'

#### **SETUP OF ROVER (R8s)**

Step 1: Turn on the Receiver R8s Rover and notice the light blinking.

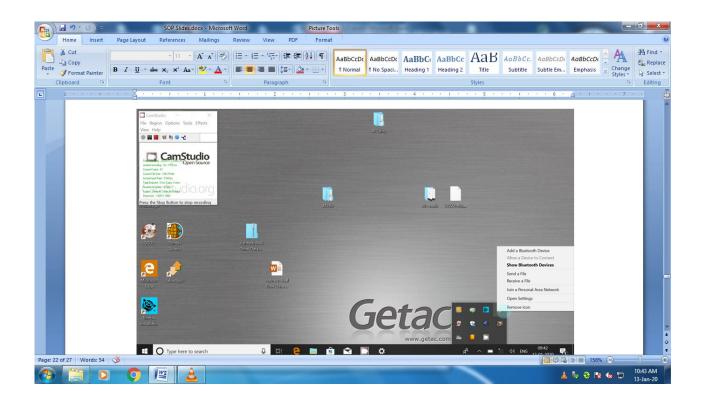


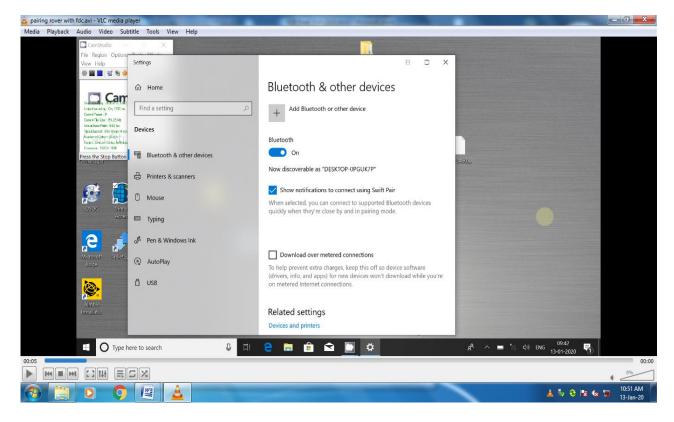
Step 2: Mount the Receiver R8s Rover on the rod provided and place it vertical exactly over the Rover station mark with the help of bipod.

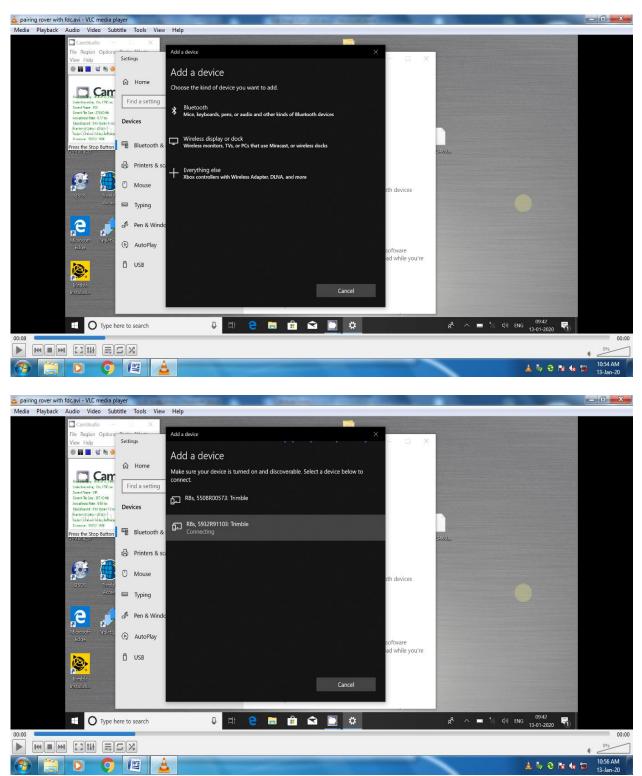
Step 3: Check the verticality of the rod viewing the bubble. Adjust the bipod legs if necessary.

Step 4: Connect Field Data Collector (Getac tab) to Wi Fi internet connection.

Step 5: Pair Field Data Collector (Getac tab) to the receiver R8s Rover with Bluetooth connectivity.Forthis go to Bluetooth icon in Field Data Collector (Getac tab), Add and pair Bluetooth device i.e. Rover, by steps shown in the following slides serially.

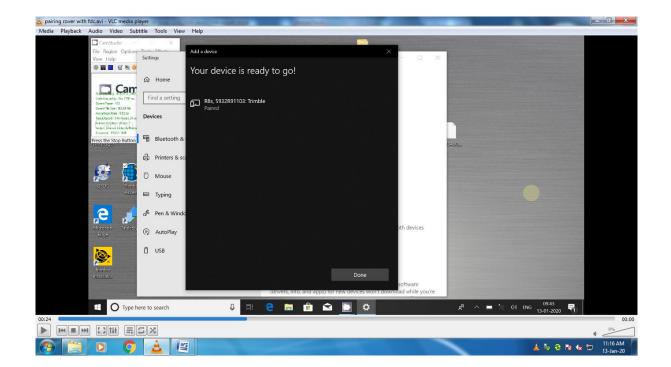


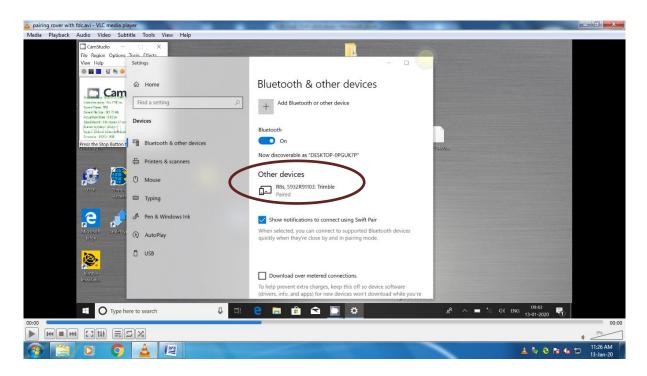




Step 6: Enter default PIN 0000 and click Connect tab. Your device is ready to go! message will be displayed for paired device R8s receiver and will reflect in the Settings window.

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Step 7: Open Trimble Access application on the tab.



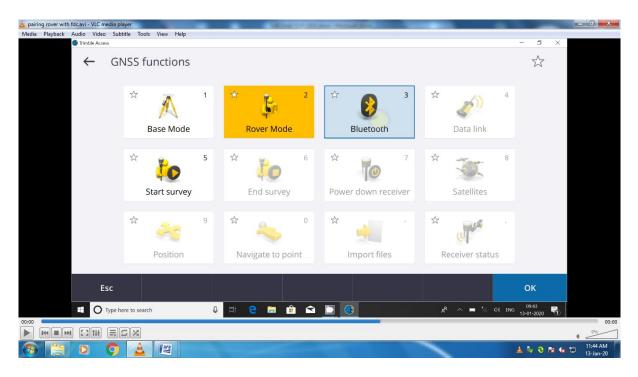
Step 8: Main window will open up. Click on NW corner tab as shown in the following slide.

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Step 9: Click Instrument and GNSS functions.

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Step 10: Choose Bluetooth icon and clickOK tab as shown below. Bluetooth window will open up.



Step 11: Select paired Trimble R8s Rover receiver, which is just paired, for first two drop down menus as shown below and click Accept tab. Press Esc tab to return to main menu.

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| Connect to GNSS rover                               |                | Connect to GNSS base     |                             |                                   |      |
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| Connect to conventional instrument                  |                | Connect to active target |                             |                                   |      |
| R8s, 5932R91103: Trimble 🔹                          |                | None                     | •                           |                                   |      |
| Connect to TDL2.4                                   |                | Connect to auxiliary GPS |                             |                                   |      |
| None  |                | None                     | •                           |                                   |      |
| Connect to laser                                    |                | Send ASCII data to       |                             |                                   |      |
| None  |                | None                     | •                           |                                   |      |
| Connect to echo sounder                             |                | Connect to printer       |                             |                                   |      |
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Now Getac tab and Rover receiver both have been paired, connected, configured and ready to use. Step 12: Click New tab to create a new project. New project window will open up.

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Step 13: Provide a Name and Description (optional) to the project.

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Step 14: Click Create tab at SE corner. New job window will open up. Step 15: Provide a job name and click on Coord. Sys. Select coordinate system window will open up.

| Create from t       | template | Create from JobX   | ML or DC file |  |
|---------------------|----------|--------------------|---------------|--|
| Job name            | RTK DEMO |                    |               |  |
| Template            | Default  |                    |               |  |
| Properties          |          |                    |               |  |
| Coord. sys.         |          | Scale: 1.000000000 |               |  |
| Units (Dist.)       |          | Meters             |               |  |
| Linked files        |          | None               |               |  |
| Active map          |          | None               |               |  |
| Feature library     |          | None               |               |  |
| Cogo settings       |          | Ground             |               |  |
| Additional settings |          | Off                | 2             |  |

Step 16: Click radio button of Select from library as shown below and click Next tab.

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|        | Select coordinate system |           |   |
|        | Scale factor only        |           |   |
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|        | Key in parameters        |           |   |
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Step 17: Select System, Zone, Datum and fill the approx. height of the terrain and click store tab.

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| ≡       | E Select coordinate system             |             |                   |     |            |
| :       | System                                 | Zone        |                   |     |            |
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|         | Datum                                  |             |                   |     |            |
|         | WGS 1984 (7P) 🔻                        |             |                   |     |            |
|         | Use geoid model<br><b>No</b>           |             |                   |     |            |
| ļ       | Use datum grid                         | Coordinates |                   |     |            |
|         | No                                     | Grid 🔻      |                   |     |            |
|         | Project height                         |             |                   |     |            |
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Step 18: Click Enter tab at SE corner.

Click on units and check the details as follows

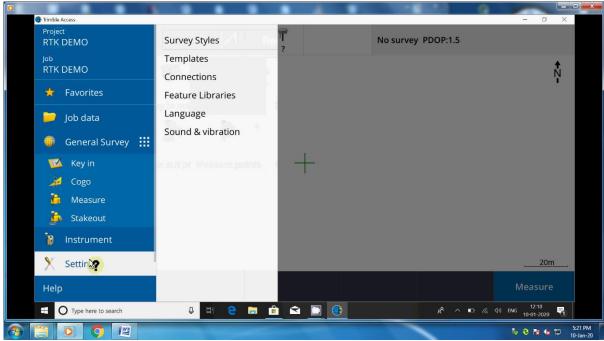
Click on Additional settings and check the details as follows

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| Properties   |            |                  |          |  |   |           |            |                       |
| Coord. sys.  |            |                  |          | 43 North (World wide/UTM)  |   |           |            |                       |
| Units (Dist.)  |            |                  |          | Meters   |   |           |            |                       |
| Linked files   |            |                  |          | None   |   |           |            |                       |
| Active map   |            |                  |          | None   |   |           |            |                       |
| Feature library  |            |                  |          | None   |   |           |            |                       |
| Cogo settings  |            |                  |          | Ground   |   |           |            |                       |
| Additional settings  |            |                  |          | CSV file   |   |           |            |                       |
| Media file   |            | Full-screen Snip |          | Previous point   |   |           |            |                       |
| Reference  | ?          |                  |          |  |   |           |            |                       |
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| k on accept<br>Units<br>Distance and grid coord<br>Meters<br>Angles<br>DDD.MMSS<br>Temperature<br>Celsius<br>Grade<br>Percent  | ds         |                  |          | Meters<br>Quadrant bearings<br>Pressure<br>Millibar<br>Area  | • |           | -          | - 0                   |
| k on accept<br>Units<br>Distance and grid coord<br>Meters<br>Angles<br>DDD.MMSS<br>Temperature<br>Celsius<br>Grade<br>Percent<br>Volume<br>Cubic meters                                  | ds         |                  |          | Meters<br>Quadrant bearings<br>Pressure<br>Millibar<br>Area  | • |           |            | - 0                   |
| k on accept<br>Units<br>Distance and grid coord<br>Meters<br>Angles<br>DDJ.MMSS<br>Temperature<br>Celsius<br>Grade<br>Percent<br>Volume  | ds         |                  |          | Meters Quadrant bearings Pressure Millibar Area Square meters  | • |           |            | - 0                   |
| k on accept<br>be Access<br>Units<br>Distance and grid coord<br>Meters<br>Angles<br>DDD.MMSS<br>Temperature<br>Celsius<br>Grade<br>Percent<br>Volume<br>Cubic meters<br>Distance display | ds         | •<br>•<br>•      |          | Meters         Quadrant bearings         Quadrant bearings         Pressure         Millibar         Area         Square meters         Coordinate display | • |           | -          | - 0                   |

| Trimble Access      |   |   |      |  |            | - | ٥                  | × |
|---------------------|---|---|------|--|------------|---|--------------------|---|
| Units               |   |   |      |  |            |   |                    |   |
| Grade               |   |   |      | Area   |            |   |                    |   |
| Percent             | • |   |      | Square meters  | •          |   |                    |   |
| Volume              |   |   |      |  |            |   |                    |   |
| Cubic meters        | • |   |      |  |            |   |                    |   |
| Distance display    |   |   |      | Coordinate display   |            |   |                    | 1 |
| 0.001               | • |   |      | 0.001  | •          |   |                    |   |
| Area display        |   |   |      | Volume display   |            |   |                    |   |
| 0.001               | • |   |      | 0.001  | •          |   |                    |   |
| Angle display       |   |   |      | Lat / Long   |            |   |                    |   |
| 1"                  | • |   |      | DDD.MMSS   | •          |   |                    |   |
| Coordinate order    |   |   |      | Station display  |            |   |                    |   |
| North-East-Elev     |   |   |      | 1+000.0  | •          |   |                    |   |
| Laser VA display    |   |   |      | Time format  |            |   |                    |   |
| Inclination         | • |   |      | Local date/time  | •          |   |                    |   |
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| Trimble Access                 | - | đ                  | × |
|--------------------------------|---|--------------------|---|
| Additional settings            |   |                    |   |
| Descriptions                   |   |                    |   |
| Use descriptions               |   |                    |   |
| No                             |   |                    |   |
| Feature library                |   |                    |   |
| Use attributes of base code    |   |                    |   |
|                                |   |                    |   |
| Point name range for job       |   |                    |   |
| Apply point name range         |   |                    |   |
| No                             |   |                    |   |
| Add to CSV file                |   |                    |   |
|                                |   |                    |   |
| Enable CSV file name abc       |   |                    |   |
|                                |   |                    |   |
| Esc                            | A | ccept              |   |
| Type here to search O Hi 🔮 😪 🖢 |   | 2:16 PM<br>28/2020 | 5 |

Step 19: Click on the NW corner tab on the main screen to select Settings and then Survey Styles. Survey Styles window will open up.



Step 20: Click New tab. Style details window will open up.

| ■ Survey S    | tyles |               |                     |                       |           |
|---------------|-------|---------------|---------------------|-----------------------|-----------|
| Name          | ^     | Size Modified | Location            |                       |           |
| IS Rover      |       | 2kb 10/1/2020 | C:\ProgramData\Trin | nble\Trimble Data\Sys | tem Files |
| RTK           |       | 2kb 10/1/2020 | C:\ProgramData\Trin | nble\Trimble Data\Sys | tem Files |
| SX10          |       | 2kb 10/1/2020 | C:\ProgramData\Trin | nble\Trimble Data\Sys | tem Files |
| VX & S Series |       | 2kb 10/1/2020 | C:\ProgramData\Trin | nble\Trimble Data\Sys | tem Files |
|               |       |               |                     |                       |           |
|               |       |               |                     |                       |           |
| Esc           | New   | Сору І        | Delete Options      |                       | Edit      |

Step 21: Provide the Style name and Survey type. Click Accept tab. New window will open up.

| rover2 | Imble Access                   |                         | - 0 ×                     |
|--------|--------------------------------|-------------------------|---------------------------|
|        | E Style details                |                         |                           |
|        | Style name                     | Style type              |                           |
|        | RTK DEMO GRB                   | GNSS 🙀 🔻                |                           |
|        |                                | GNSS                    |                           |
|        |                                | Conventional            |                           |
|        |                                | Integrated Surveying    |                           |
|        |                                |                         |                           |
|        |                                |                         |                           |
|        |                                |                         |                           |
|        |                                |                         |                           |
|        |                                |                         |                           |
|        |                                |                         |                           |
|        |                                |                         |                           |
|        | Esc                            |                         | Accept                    |
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- 0 ×

Step 22: Click Edit tab for Rover options. Rover options window will open up.

| rover2 | imble Access   | o x                     | :: |
|--------|--|-------------------------|----|
|        | E RTK DEMO GRB   |                         |    |
|        | Rover options  |                         |    |
|        | Rover data link  |                         |    |
|        | Base options   | - 15                    |    |
|        | Base data link   | - 15                    |    |
|        | Compensated point  | - 15                    |    |
|        | Topo point   | - 15                    |    |
|        | Observed control point   | - 15                    |    |
|        | Rapid point  | - 15                    |    |
|        | Continuous points  | - 11                    |    |
|        | Stakeout   | - 11                    |    |
|        | Site calibration   | - 11                    |    |
|        | Dunlicate point tolerance  |                         |    |
|        | Esc Store E  |                         |    |
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|        | P Type here to search       ○     봄     Ê     E </td <td>NG 18:58<br/>10-01-2020</td> <td>3</td> | NG 18:58<br>10-01-2020  | 3  |

Step 23: Provide the information as shown in the slide below.

| mble Access                   |   |   |    |   |                              |   |   | - 0                   | × |  |  |  |  |
|-------------------------------|---|---|----|---|------------------------------|---|---|-----------------------|---|--|--|--|--|
| Rover options Survey type RTK |   |   |    |   | Broadcast format<br>RTCM3Net | • | BROADCAST FORMA<br>WILL BE RTCM3Net (<br>VRS (RTCM) FOR<br>CORS |                       |   |  |  |  |  |
| Antenna                       |   |   |    |   |                              |   | Conto   |                       |   |  |  |  |  |
| Туре                          |   |   |    |   | Measured to                  |   |   |                       |   |  |  |  |  |
| R8s Internal                  | • |   |    |   | Bottom of antenna mount      | • |   |                       |   |  |  |  |  |
| Antenna height                |   |   |    |   | Part number                  |   |   |                       |   |  |  |  |  |
| 2.000m                        |   |   |    |   | 97080-xx                     |   |   |                       |   |  |  |  |  |
| Serial number                 |   |   |    |   |                              |   |   |                       |   |  |  |  |  |
| ?                             |   |   |    |   |                              |   |   |                       |   |  |  |  |  |
| Elevation mask                |   |   |    |   |                              |   |   |                       |   |  |  |  |  |
| 10°                           |   |   |    | • |                              |   |   |                       |   |  |  |  |  |
| PDOP mask                     |   |   |    |   |                              |   |   |                       |   |  |  |  |  |
| 3.0                           |   |   |    | • |                              |   |   |                       |   |  |  |  |  |
|                               |   |   |    |   |                              |   | _   |                       |   |  |  |  |  |
| Esc                           |   |   |    |   |                              |   |   | Accept                |   |  |  |  |  |
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#### Step 24: Provide Serial number of R8s receiver (Optional).

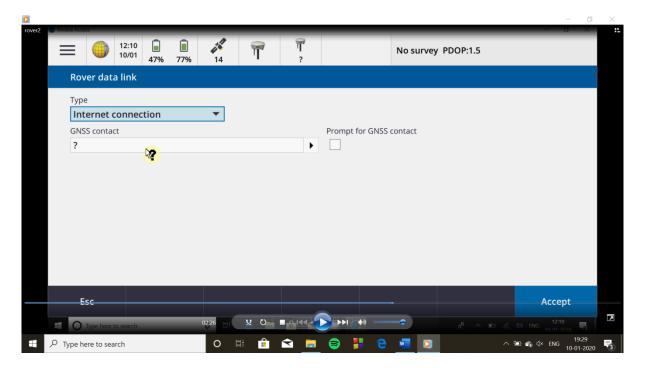
| Trimble Access       |        |                       |            | -   | D             | ×   |
|----------------------|--------|-----------------------|------------|-----|---------------|-----|
| Rover options        |        |                       |            |     |               |     |
| Elevation mask       |        |                       |            |     |               | 4.5 |
| 10°                  |        | •                     |            |     |               |     |
| PDOP mask            |        |                       |            |     |               |     |
| 3.0                  |        | •                     |            |     |               |     |
| GNSS Signal Tracking |        |                       |            |     |               | 1   |
| GPS                  |        | Use L2e<br><b>Yes</b> |            |     |               |     |
| GPS L2C              |        | L5                    |            |     |               |     |
| GLONASS              |        | Galileo 🗸             |            |     |               |     |
| QZSS                 |        | BeiDou                |            |     |               |     |
| Esc                  |        |                       |            | Acc | cept          |     |
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Step 25: Elevation mask and PDOP mask default values can be altered if required. Step 26: GNSS Signal Tracking can be checked for desired constellations. Click Accept tab. Again, we will come back to new window.

Step 27: Click Edit tab for Rover data link. Rover data link window will open up.

| rover2 | Trimble Access                   | _                               | - 0 ×             |  |
|--------|----------------------------------|---------------------------------|-------------------|--|
|        | RTK DEMO GRB                     |                                 | _                 |  |
|        | 1600                             |                                 |                   |  |
|        | Rover options                    |                                 |                   |  |
|        | Rover data link                  |                                 |                   |  |
|        | Base options                     |                                 |                   |  |
|        | Base data link                   |                                 |                   |  |
|        | Topo point                       |                                 |                   |  |
|        | Observed control point           |                                 |                   |  |
|        | Rapid point                      |                                 |                   |  |
|        | Continuous points                |                                 |                   |  |
|        | Stakeout                         |                                 |                   |  |
|        | Site calibration                 |                                 |                   |  |
|        | Duplicate point tolerance        |                                 |                   |  |
|        | Lasor rangefinder                |                                 |                   |  |
|        | Esc Store                        |                                 | dit               |  |
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Step 28: Select Type as Internet connection. Click on GNSS contact. A GNSS contact list will come up.



Step 29: Select desired GNSS contact, edit existing or create a new GNSS contact. Accordingly, a new window will open up.

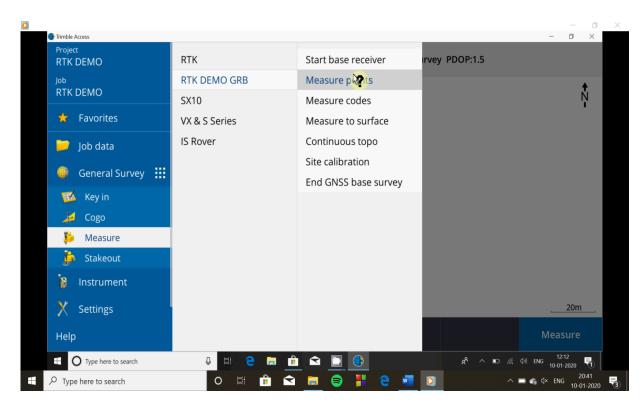
Step 30: Here we will provide the IP address of Remote Server and IP Port of communicating Rover. IP Port will be unique for communicating Rover. There may be other Rovers communicating to the same server but IP Port will be different for different Rovers. Below a new GNSS contact SOI SERVER SGW has been created. Click the Store tab.

| 2 GNSS contacts Name RTKBASEGROUND   | No servey PDOP15   |  |  |  |  |  |  |
|--|--|--|--|--|--|--|--|
|  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |
| Inter Bedroone   | <ul> <li>Type</li> <li>Internet rover</li> </ul>   |  |  |  |  |  |  |
| RTKDEMO  | Internet rover   |  |  |  |  |  |  |
| RTKSERVERGRB   | Internet rover   |  |  |  |  |  |  |
| SOI RTK  | Internet rover   |  |  |  |  |  |  |
| SOI SERVER   | Internet rover   |  |  |  |  |  |  |
| Esc New Delete Copy  | Edit Accept  |  |  |  |  |  |  |
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| ble Access   | Image: Contract of the second seco |  |  |  |  |  |  |
| Edit GNSS contact  |  |  |  |  |  |  |  |
| Name Route thro<br>kgdc Performance Performa | ough controller<br>es  |  |  |  |  |  |  |
| NTRIP Configuration  |  |  |  |  |  |  |  |
| Use RTX (Internet) Use NTRIP   | 25   |  |  |  |  |  |  |
|  | Use proxy server   |  |  |  |  |  |  |
| Connect directly to Mountpoint NTRIP use   |  |  |  |  |  |  |  |
| No vikram  |  |  |  |  |  |  |  |
| NTRIP password   |  |  |  |  |  |  |  |
| •••••  |  |  |  |  |  |  |  |
| IP Address IP Port   |  |  |  |  |  |  |  |
| Esc  | Store  |  |  |  |  |  |  |
|  | Ĵ ∧ 🐑 12:20 PM<br>8/28/2020  |  |  |  |  |  |  |
| NTRIP user name dgrb1<br>or<br>dgrb2<br>or<br>dgrb3<br>NTRIP password dgrb1<br>or<br>or<br>dgrb2<br>dgrb2  | Ip Address<br>103.205.244.106<br>Port 2101   |  |  |  |  |  |  |

| Trimble  | e Access     |                |       |             |              |      |   |    |                |              |  |           |        |       |   |   |    | - 0                  | ×      |
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| R        | lover dat    | a link         |       |             |              |      |   |    |                |              |  |           |        |       |   |   |    |                      |        |
| T        | уре          |                |       |             |              |      |   |    |                |              |  |           |        |       |   |   |    |                      |        |
|          | Internet o   | connect        | ion   |             | -            |      |   |    |                |              |  |           |        |       |   |   |    |                      |        |
| G        | NSS conta    | ct             |       |             |              |      |   |    |                | Promp        | ot for GNS   | S contact |        |       |   |   |    |                      |        |
| L        | kgdc         |                |       | _           |              |      |   |    | •              | $\checkmark$ |  |           |        |       |   |   |    |                      |        |
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|          |              |                |       |             |              |      |   |    |                |              |  |           |        |       |   |   |    |                      |        |
|          |              |                |       |             |              |      |   |    |                |              |  |           |        |       |   |   |    |                      |        |
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|          | lumber of r  | measurer       | ments |             |              |      |   |    |                |              |  |           |        |       |   |   |    |                      |        |
|          | 20           |                |       |             |              |      |   |    |                |              |  |           |        |       |   |   |    |                      |        |
|          | Precision    | 1              |       |             |              |      |   |    |                |              |  |           |        |       |   |   |    |                      |        |
| 1        | Auto tolera  | nce            |       |             |              |      |   |    |                |              |  |           |        |       |   |   |    |                      |        |
| [        | No           |                |       |             |              |      |   |    |                |              |  |           |        |       |   |   |    |                      |        |
|          | Horizontal   | tolerance      | 2     |             |              |      |   |    |                |              | al toleranc  | e         |        |       |   |   |    |                      |        |
|          | 0.015m       |                |       |             |              |      |   |    | •              | 0.03         | Om   |           |        |       |   |   |    | •                    | ×.     |
|          | Store RTK i  | nitialized     | only  |             |              |      |   |    |                |              |  |           |        |       |   |   |    |                      |        |
|          | $\checkmark$ |                |       |             |              |      |   |    |                |              |  |           |        |       |   |   |    |                      |        |
| Δ        | uto abandi   | on             |       |             |              |      |   |    |                |              |  |           |        |       |   |   |    |                      |        |
|          | Esc          |                |       |             |              |      |   |    |                |              |  |           |        |       |   |   |    | Accept               |        |
|          | D Type h     | nere to se     | arch  |             |              | C    | ) | ЦI | R              |              |  |           |        |       | Û | ^ | D  | 1:13 PM<br>8/28/2020 | $\Box$ |

Step 31: Click Accept tab. We will return to main menu.

Step 32: Click Measure, select your Survey style and select Measure points as shown below



Step 33: Processing bar will appear for establishing connection to the Server.

| Trimble Access  |   | - 0 ×                                   |
|---|---|---|
| 12:12<br>10/01  | Image: Construction         Image: Construction |   |
| <b>. h</b>  | · · · · · · · · · · · · · · · · · · ·   | <b>↑</b>                                |
| E Company and a |   |   |
| <b>E</b>  |   |   |
| Q   | Please wait   |   |
| ୍   | Establishing connection   |   |
| ¢   | Cancel  |   |
|   |   |   |
| 8   |   |   |
| 1   |   | 20m                                     |
|   |   | <u>20m</u>                              |
|   |   | Measure                                 |
| Type here to search   | u 🗎 😑 🚍 🚖 🔄 📵 👘 🖈 🖚   | 差 句》 ENG 12:12<br>10-01-2020 <b>で</b> 1 |
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| 🕒 Trimb | le Access   |   |          |           |    |               |               |     |        |        |         |        |    |        | - 0                  | ×     |
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| Sele    | ect data so | urce                                    |          |           |    |               |               |     |        |        |         |        |    |        |                      |       |
| Mo      | ount point  | Identifier                              | Distance | e ^ Forma | at | Form          | at deta       | ils | Carrie | r      | Nav Sy  | stem   | Ne | etwork | k C                  | ountr |
| so      | IB          | SOIB                                    |          | RTCM      | 3  |               | L2 GPS+GLO+GA |     |        |        |         |        |    |        |                      |       |
|         | Select th   | all format<br>e format to<br>S the form | be used  | and click | -  | <u>p</u> t    |               |     |        |        |         |        |    |        |                      |       |
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|         | Esc         | All                                     |          | Refresh   |    |               |               |     |        |        |         |        |    |        | Accep                | ot    |
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Step 34: A tick will be displayed after successful connection as shown below in circle.

| ● Trimble Access                        | - 🗇 ×  |
|---|--|
| ► N                                     | Measure points 🔶 📩                                       |
|   | Point name 3 Code ABC Abc Antenna height (Uncorr) 2.000m |
|   | Measured to  |
| 20m                                     | Time so farOm2sEpochs remaining2                         |
| Esc                                     | Options 🧟  |
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Step 35: click in option and select QC1&QC2

Step 36: RTK solution will be Float or Fix as shown in the circle below. Point name, Code and Antenna height can be provided if accepted. To accept click on SE corner tab as shown below. More points can be measured if we continue to store points.

| Trimble Access         |  |                         |                           | - 0 ×       |
|------------------------|--|-------------------------|---------------------------|-------------|
|                        | 2:19 a b c c c c c c c c c c c c c c c c c c | ₩ <sup>™</sup><br>2.000 | RTK:Float H:0.65m V:1.30m |             |
| •                      |  |                         | RTK:FIXED H:0.012m        | *           |
| E.                     |  |                         | Point pame                |             |
| <b>€</b>               |  |                         | 3<br>Code                 | •           |
| Q                      |  |                         | ABC                       | •           |
| Q                      |  |                         | Topo point                |             |
| ¢                      |  | -                       | Antenna height (Uncorr)   |             |
|                        |  |                         | 2.000m                    | •           |
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| ~                      |  |                         | Time so far               | 0m2s        |
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| Esc                    |  |                         | Options                   |             |
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| Trimble Access   |                              |                           | – d ×                     |
| Continue and stor  | re point?                    |                           |                           |
| Confirm<br>• Waiting for initialized solu<br>• Poor precision (Horizontal<br>• Required number of meas | l: 0.432m, Vertical: 0.903m) |                           |                           |
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The Rover point collected will instantly give corrected coordinates with respect to Base.

# SOP for Export RTK data file

Click on Trimble Access in your FDC (Getac)



### Open your RTK project

| Trimble Access |                   |           |           |   |          | _          |                        | - 0                                 | × |
|----------------|-------------------|-----------|-----------|---|----------|------------|------------------------|-------------------------------------|---|
| ≡              | Projects          |           |           | C | <b>~</b> | RTK DEM    | 0                      |                                     | : |
| New            | Filter project    |           | Last used | ^ | Y        | RTK IN GRB |                        |                                     |   |
|                |                   |           |           |   |          | Jobs (1)   |                        |                                     |   |
| Ō              | RTK DEMO          |           |           |   |          | RTK DEMO   |                        |                                     |   |
|                |                   |           | 14:26     |   |          |            |                        |                                     |   |
| 6              | san               |           |           |   |          |            |                        |                                     |   |
|                |                   |           | 10/1/2020 |   |          |            |                        |                                     |   |
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| 🗄 О Туре       | here to search    | 0 🖬 🤤 🔚   | 1         |   |          |            | x <sup>a</sup> ^ 🗈 *a. | <b>վ</b> ッ) ENG 15:01<br>14-01-2020 | - |
| Open you       | ur RTK Job (eg. I | RTK DEMO) |           |   |          |            |                        |                                     |   |

| Trimble Access |                |         |                |            |                   | - 0                | $\times$   |
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| $\leftarrow$   | RTK DEMO       |         | C              | RTK D      | EMO               |                    | :          |
| New            | Filter job     | L       | ast used \land | Status     |                   |                    |            |
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| $(\oplus)$     | RTK DEMO       |         |                |            |                   |                    |            |
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#### Now click on Export tab in your FDC

| ne Access            |   |   |                          |   | - 0    |
|----------------------|---|---|--------------------------|---|--------|
| Export               |   |   |                          |   |        |
| File format          |   | F | ïle name                 |   |        |
| CSV WGS-84 lat longs | • |   | RTK DEMO.csv             |   |        |
| View created file    |   | L | atitude/Longitude format |   |        |
| $\checkmark$         |   |   | DMS degrees              | • |        |
| Use DMS symbols      |   | ι | Jse hemisphere character | s |        |
| Yes                  | - |   | Yes                      | • |        |
|                      |   |   |                          |   |        |
|                      |   |   |                          |   |        |
| Esc                  |   |   |                          |   | Accept |

Export page will open.

Different File formats are given. Here select file format as "CSV WGS-84 lat longs"

In "File name" select your desired path

Select "Accept"

Now file has been exported in Lat Long format as path given and file will be opened in MS excel.

#### Again you will be back in your Job page

| · RTK  | DEMO          |         |           | C  | RTK D                          | DEMO                                  |  |
|--|---------------|---------|-----------|--|--------------------------------|---------------------------------------|--|
| New Filter   | iob           |         | Last used | ~ T  | Status                         |                                       |  |
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| O Type here to sear<br>ort page w<br>Access<br>E Export<br>File format<br>CSV WGS-84 I                       | ill display a | u 🖶 e 🖻 |           | File name  | <b>O.csv</b><br>ngitude format | t ⊡ ∧ %<br>                           | ₹ 40 ENG 15:01<br>14:01-2020<br>- 10<br> |
| O Type here to sear<br>ort page w<br>Access<br>E Export<br>File format<br>CSV WGS-84 Ia<br>View created file | ill display a | u 🖶 e 🖻 |           | File name<br>RTK DEM<br>Latitude/Lor<br>DMS degu | <b>O.csv</b><br>ngitude format | x <sup>2</sup> ∧ ₪ '                  | ₹ 40 ENG 15:01<br>14:01-2020<br>- 10<br> |

Now we have to take coordinate in Easting & Northing format. So select "Comma delimited (\*.CSV,\*.TXT)" in File Format.

| Trimble Access              |           |                   |                      | - 0 ×                                |
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| ≡ Export                    |           |                   |                      | $\Delta$                             |
| File format                 |           | File name         |                      |                                      |
| Comma Delimited (*.CSV, *.T | XT) 🔻     | RTK DEMO.csv      |                      |                                      |
| Point name                  |           | Point code        |                      |                                      |
| Field1                      | •         | Field5            | -                    |                                      |
| Northing                    |           | Easting           |                      |                                      |
| Field2                      | •         | Field3            | -                    |                                      |
| Elevation                   |           | View created file |                      |                                      |
| Field4                      | •         | $\checkmark$      |                      |                                      |
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# In "File name" select your desired path Select "Accept"

| Selec<br>Trimble Ac |             | ept            |             |   |    |          |   |   |  |  |  |   |     |   |         | _         | ٥   | ×  |
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| Selec               | t points    |                |             |   |    |          |   |   |  |  |  |   |     |   |         |           |     |    |
| Enter               | ' single    | point r        | name        |   |    |          |   |   |  |  |  |   |     |   |         |           |     |    |
| Selec               | t from l    | ist            |             |   |    |          |   |   |  |  |  |   |     |   |         |           |     |    |
| All gr              | id point    | S              |             |   |    |          |   |   |  |  |  |   |     |   |         |           |     |    |
| All ke              | eyed in p   | oints          |             |   |    |          |   |   |  |  |  |   |     |   |         |           |     | L  |
| Point               | s withir    | n radiu        | s           |   |    |          |   |   |  |  |  |   |     |   |         |           |     | L  |
| All po              | oints       |                |             |   |    |          |   |   |  |  |  |   |     |   |         |           |     | L  |
| Point               | s with s    | ame c          | ode         |   |    |          |   |   |  |  |  |   |     |   |         |           |     | L  |
| Point               | s by na     | me rar         | nge         |   |    |          |   |   |  |  |  |   |     |   |         |           |     | L  |
| Secti               | on of jo    | b              |             |   |    |          |   |   |  |  |  |   |     |   |         |           |     |    |
| Curre               | ent map     | select         | ion         |   |    |          |   |   |  |  |  |   |     |   |         |           |     | з. |
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|                     | Type here t | o search       |             | Û | ⊒i | <b>e</b> | = | î |  |  |  | ٩ | ^ ع | • | ⊂()) EM | NG 14-01- |     | 2  |

Select "All points" from options and click on Accept. Now file has been exported in Easting & Northing format as path given and file will be opened in MS excel.

#### **R8S INTERNAL STATIC**

For static observation we have to first create the job & survey style using Trimble access in your field controlling device.

Open Trimble Access a default window will open

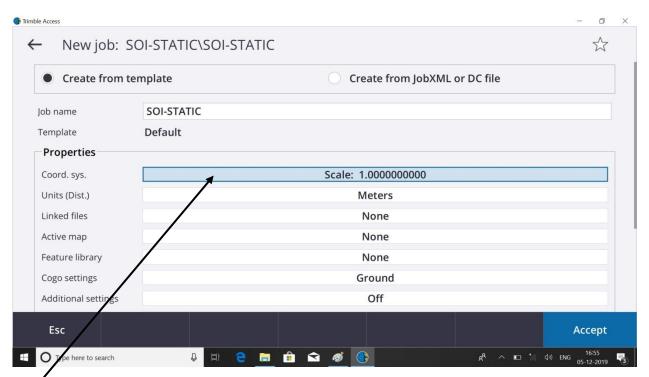
| Trimble Access |                   |         |               |          |                                       | - 8 ×  |
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|                | Projects          |         | C             | <b>i</b> | SOI RTK                               | :  |
| New            | Filter project    |         | Last used 🛛 🔨 | Y        | Jobs (1)<br>SOI RTK                   |  |
| Ō              | SOI RTK           |         | 12:22         |          |                                       |  |
| Ō              | R8s-static        |         | 11:03         |          |                                       |  |
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To create a new project, click on new.

| 🕕 Trimt | ble Access                      |                 |                   |           | ٥   | ×        |
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| ~       | <ul> <li>New project</li> </ul> |                 |                   |           |     |          |
|         |                                 |                 |                   |           |     |          |
|         | Name                            | SOI-STATIC      |                   |           |     |          |
|         | Description                     | 2               |                   |           |     |          |
|         | Reference                       | ?               |                   |           |     |          |
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Give the name of your project, n click on create.

A new job window will open. Give the job name



#### Click here to set the coordinate system.

| 🚯 Trim | ble Acces | is              |             |         |      |   |  |   |          |  |   |     |                   | -              | ٥  | × |
|--------|-----------|-----------------|-------------|---------|------|---|--|---|----------|--|---|-----|-------------------|----------------|----|---|
| Ξ      | =         | Select          | coordir     | nate sy | stem |   |  |   |          |  |   |     |                   |                |    |   |
|        | Sel       | ect coor        | dinate sys  | tem     |      |   |  |   |          |  |   |     |                   |                |    |   |
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|        | Φ         | Key in p        | parameter   | S       |      |   |  |   |          |  |   |     |                   |                |    |   |
|        | $ \phi $  | No proj         | jection / n | o datum |      |   |  |   |          |  |   |     |                   |                |    |   |
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Click the option –"Select from Library"

| Trim | ble Access                   |        |   |          |          |             |        |                              | -                     | o x         |
|------|------------------------------|--------|---|----------|----------|-------------|--------|------------------------------|-----------------------|-------------|
| =    | Select coordinate            | system |   |          |          |             |        |                              |                       |             |
|      | System                       |        |   |          |          | Zone        |        |                              |                       |             |
|      | World wide/UTM               | •      |   |          |          | 44 North    |        | •                            |                       |             |
|      | Datum                        |        |   |          |          |             |        |                              |                       |             |
|      | WGS 1984 (7P)                |        | • |          |          |             |        |                              |                       |             |
|      | Use geoid model              |        |   |          |          |             |        |                              |                       |             |
|      | No                           |        |   |          |          |             |        |                              |                       |             |
|      | Use datum grid               |        |   |          |          | Coordinates |        |                              |                       |             |
|      | No                           |        |   |          |          | Grid        |        | -                            |                       |             |
|      | Project height               |        |   |          |          |             |        |                              |                       |             |
|      | 648.000m                     |        |   |          | •        |             |        |                              |                       |             |
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|      | Esc                          |        |   |          |          |             | Key in |                              | Stor                  | e           |
|      | <b>O</b> Type here to search | Q H C  |   | <b>*</b> | <b>¬</b> | 🧭 🍈         |        | x <sup>R</sup> ^ 🖬 *//. (4)) | ) ENG 16:5<br>05-12-2 | 6<br>2019 🖏 |

Select the coordinate system, Zone, Datum& approximate project height, and click on store.

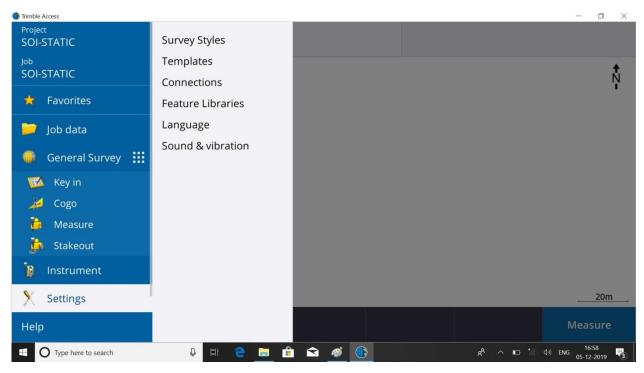
You will be redirected to the job property page. Rest all the settings are by default.

| 🚯 Trim | ble Access            |                           | -          | ٥                 | × |
|--------|-----------------------|---------------------------|------------|-------------------|---|
| ÷      | – Job properti        | ies: SOI-STATIC           |            | $\Leftrightarrow$ |   |
|        | Coord. sys.           | 44 North (World wide/UTM) |            |                   |   |
|        | Units (Dist.)         | Meters                    |            |                   |   |
|        | Linked files          | None                      |            |                   |   |
|        | Active map            | None                      |            |                   |   |
|        | Feature library       | None                      |            |                   |   |
|        | Cogo settings         | Ground                    |            |                   |   |
|        | Additional settings   | Off                       |            |                   |   |
|        | Media file            | Previous point            |            |                   |   |
|        | Reference             | ?                         |            |                   |   |
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|        | Operator              | ?                         |            |                   |   |
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Now we will create a survey style for static observation.

Click on the main menu icon o the left most corner of your field data controller.

Go to -"Settings>Survey style"



Click on new to create a new survey style

| ame ^         | Size Modified  | Location                                    |                             |              |
|---------------|----------------|---|-----------------------------|--------------|
| faststatic    | 2kb 14/10/2019 |   | mData\Trimble\Trimble Data\ |              |
| IS Rover      | 2kb 14/10/2019 |   | mData\Trimble\Trimble Data\ |              |
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| RTK           | 2kb 14/10/2019 | 9 C:\ProgramData\Trimble\Trimble Data\Syste |                             |              |
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Give the name of your" survey style, style type"

| Trimble Access                                    | - 0                    | ı × |
|---|------------------------|-----|
| E Style details                                   |                        |     |
| Style name Style type                             |                        |     |
| SOI-STATIC GNSS                                   |                        |     |
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Click on Accept.

## A new window will open.

| Trimble Access                                  | -                   | ٥ | × |
|---|---------------------|---|---|
| SOI-STATIC                                      |                     |   |   |
|   |                     |   |   |
| Rover options                                   |                     |   |   |
| Rover data link                                 |                     |   |   |
| Base options                                    |                     |   |   |
| Base data link                                  |                     |   |   |
| Compensated point                               |                     |   |   |
| Topo point                                      |                     |   |   |
| Observed control point                          |                     |   |   |
| Rapid point                                     |                     |   |   |
| Continuous points                               |                     |   |   |
| Stakeout  |                     |   |   |
| Site calibration                                |                     |   |   |
| Dunlicate point tolerance                       |                     |   |   |
| Esc Store                                       | Edi                 | t |   |
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Select –"Rover options"

| 🕕 Trim | ble Access            |       |       |                  |  | - 0                                   | × |
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| Ξ      | Rover options         |       |       |                  |  |                                       |   |
|        | Survey type           |       |       |                  |  |                                       |   |
|        | FastStatic            | •     |       |                  |  |                                       |   |
|        | Antenna               |       |       |                  |  |                                       |   |
|        | Туре                  |       |       | Measured to      |  |                                       |   |
|        | R8s Internal          | -     |       | Center of bumper | •                                      |                                       |   |
|        | Antenna height        |       |       | Part number      |  |                                       |   |
|        | 1.500m                |       | •     | 97080-xx         |  |                                       |   |
|        | Serial number         |       |       |                  |  |                                       |   |
|        | ?                     |       |       |                  |  |                                       |   |
|        | Logging device        |       |       | Logging interval |  |                                       |   |
|        | Receiver              | •     |       | 15s              | •                                      |                                       |   |
|        | Elevation mask        |       |       |                  |  |                                       |   |
|        | 10°                   |       | •     |                  |  |                                       |   |
|        | Esc                   |       |       |                  |  | Accept                                |   |
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Input your –survey style, antenna type, antenna height, logging device& logging interval.

Use Antenna measurement method-"CENTER OF BUMPER" in case of tripod

"Check in all the GNSS signal tracking" as shown below.

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| ▶            |  |  |
|              |  |  |
| Use L2e      |  |  |
| Yes          |  |  |
| L5           |  |  |
| $\checkmark$ |  |  |
| Galileo      |  |  |
| $\checkmark$ |  |  |
| BeiDou       |  |  |
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|              | Acce   | pt   |
|              | 171  | 18   |
|              | Use L2e<br>Yes<br>L5<br>✓<br>Galileo<br>✓<br>BeiDou<br>✓ | Use L2e<br>Yes<br>L5<br>I<br>Galileo<br>I<br>BeiDou<br>I |

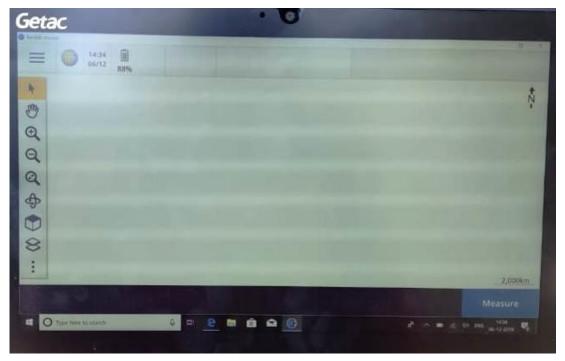
#### Click on Accept

Now you can start your static survey by centering & leveling your GNSS receiver in the ground. Switch on the power button of your GNSS R8s receiver.



Now in your field data collector unit

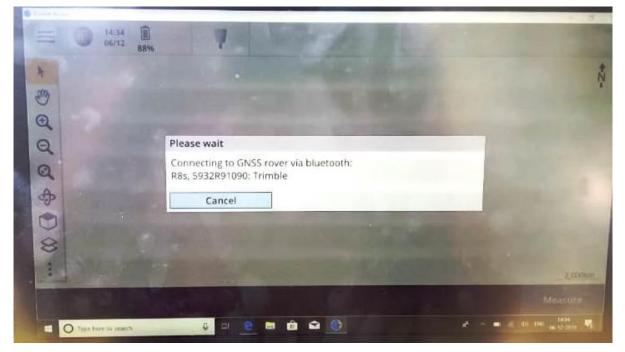
#### Open your job



Click on measure it will ask you to select your survey style, select your survey style

| R8s-static    |  |                   |  |  |
|---------------|--|-------------------|--|--|
| RTK           |  | The second second |  |  |
| SOI RTK       |  |                   |  |  |
| SOI-STATIC    |  |                   |  |  |
| SX10          |  |                   |  |  |
| VX & S Series |  |                   |  |  |
| IS Rover      |  |                   |  |  |
|               |  |                   |  |  |
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|               |  |                   |  |  |

It will now establish Bluetooth connection of your FDC to R8s Antenna



After establishing Bluetooth connection it will ask for the point name

|   | 0       | 15:03<br>06/12 819 | 82% | 22<br>22 | T          | T<br>1.220 |   |         | FastStatic PDOP:1.2                         |                   |             |
|---|---------|--------------------|-----|----------|------------|------------|---|---------|---|-------------------|-------------|
| * |         |                    |     |          |            |            |   | tN-     | Measure points                              |                   |             |
| 3 |         |                    |     |          |            |            |   | Ŷ       | Point name                                  |                   |             |
|   |         |                    |     |          |            |            |   |         | soi1  |                   | •           |
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| Q |         |                    |     |          |            |            |   |         |   |                   |             |
|   |         |                    |     |          |            |            |   |         | Method                                      | *                 |             |
| 0 |         |                    |     |          |            |            |   |         | FastStatic point<br>Antenna height (Uncorr) |                   |             |
| Ð |         |                    |     |          |            |            | + |         | 1.220m                                      |                   | >           |
|   |         |                    |     |          |            |            | 1 |         | Measured to                                 |                   |             |
|   |         |                    |     |          |            |            |   |         | Bottom of antenna mount                     | *                 |             |
| 8 |         |                    |     |          |            |            |   |         |   |                   |             |
|   |         |                    |     |          |            |            |   | 2,000km | Time to go                                  |                   | ;           |
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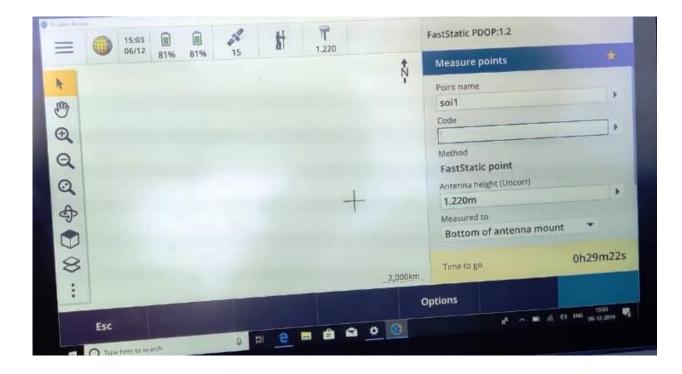
Enter the point name, choose the method fast static, and enter the instrument height.

Click on the option to enter the time interval for your static observation, a new window will open up

| Options                |                | - 0   |
|------------------------|----------------|-------|
| FastStatic point       |                |       |
| Auto store point       |                |       |
| L1/L2 FastStatic times |                |       |
| Time for 4 SVs         | Time for 5 SVs |       |
| 30m0s                  | 30m0s          |       |
| Time for 6+ SVs        |                |       |
| 30m0s                  |                |       |
| Prompt for attributes  |                |       |
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| Esc                    |                | Enter |

Click on auto store point, select the time interval for your static observation and click on enter.

You will be redirected to the previous window. And at the bottom it will show you the time remaining to complete your observation.



Static observation file is available in in the project file in the following path:

C\Program Data\Trimble\Trimble Data\"User Account"\Project\\*.t02.

This data is then processed in TBC software to get the final coordinates.

# Contents

| CREATING A NEW PROJECT                           | 2  |
|--|----|
| PROJECT SETTING                                  | 6  |
| DATA IMPORT                                      | 9  |
| PROCESSING OF BASELINE                           | 11 |
| Loop Closure                                     | 17 |
| NETWORK ADJUSTMENT                               | 19 |
| Point to be checked in Network Adjustment Report | 21 |
| Disclaimer                                       | 23 |

# STEP -1

# **CREATING A NEW PROJECT**

#### **Open the "TRIMBLE BUSSINESS CENTRE" software.**

1. Start>program files>Trimble Office> Trimble Business Centre> Trimble Business Centre



| 🕲 Trimble Business Center             |                               |                            |                 |             |       |           |          |         | _ 8 ×    |
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| Common tasks                          | TBC on the                    | Internet                   |                 |             |       |           |          |         |          |
| Start a new project                   | BC Sup                        | port                       |                 |             |       |           |          |         |          |
| 🧭 Open an existing project            | TBC Net                       | ws                         |                 |             |       |           |          |         |          |
| 🕅 Check for updates                   | facebook Vide                 | o demos on Facebook        |                 |             |       |           |          |         |          |
| Strimble Access Services              |                               | demos on YouTube           |                 |             |       |           |          |         |          |
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| Learning aids                         | Support do                    |                            |                 |             |       |           |          |         |          |
| Online Help (F1)                      | Read Me                       |                            |                 |             |       |           |          |         |          |
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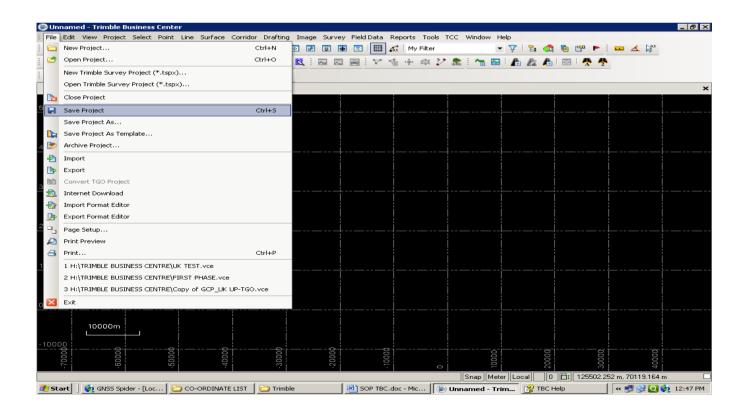
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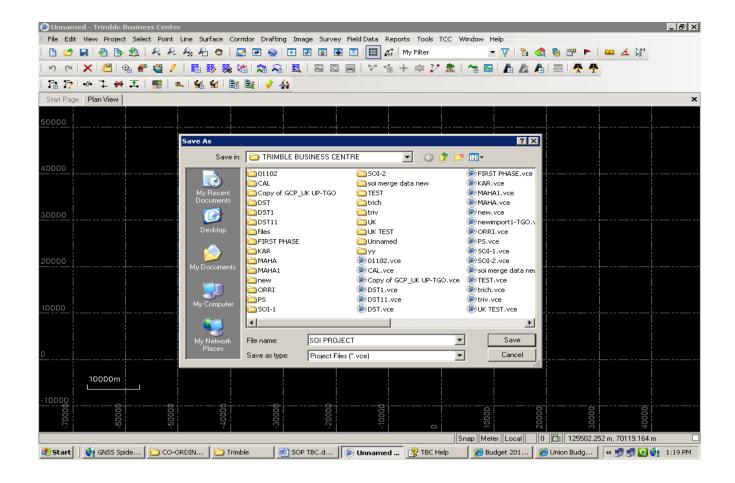
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1. Select the Following Command

Menu>File> Save Project





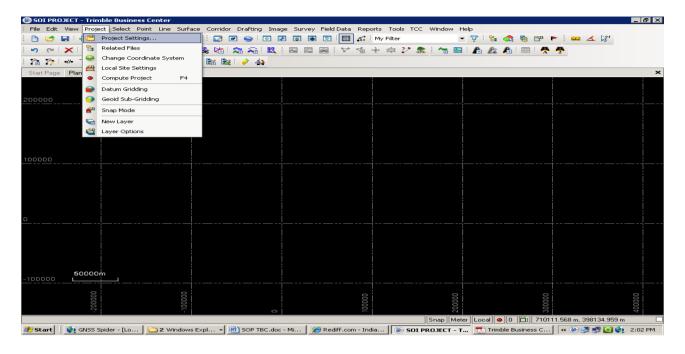
NOTE: It will save in default path: "C/Documents/Trimble Business Centre". User can save it to any specified required path.

THEN CLICK SAVE.

# **STEP 2**

# **PROJECT SETTING**

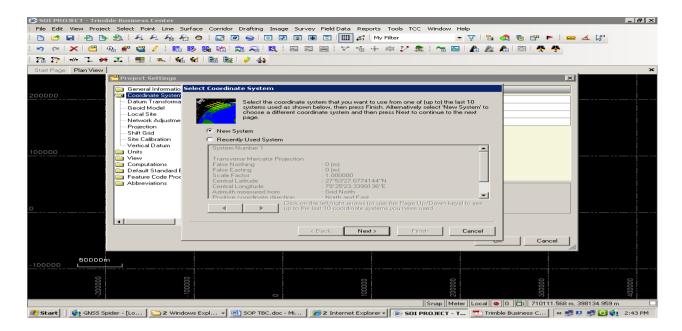
1. Menu>Project > Project Setting



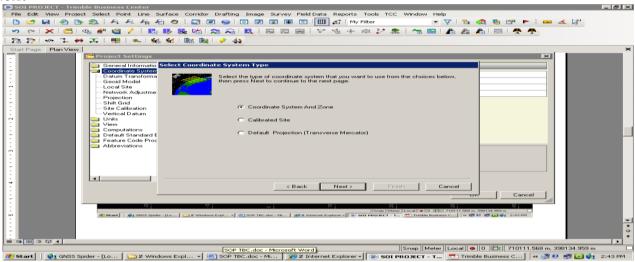
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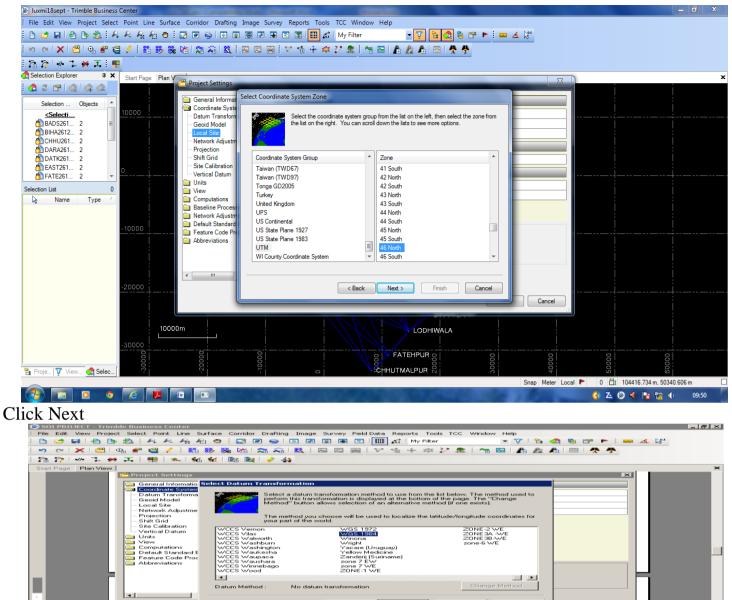
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#### Click Next



Click Next and select coordinates system as per requirement.



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# Click Next and select Geoid model (the latest geoid model is EGM -2008)

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|                      | General Information                                       | Summary                  |                         |                        |                    |                   |
| 0000                 | Coordinate System Datum Transformation                    | Coordinate system group: |                         | UTM                    |                    |                   |
|                      | Geoid Model   | Zone:                    |                         | 43 North               |                    |                   |
|                      | Local Site  | Datum transformation:    |                         | WGS 1984 (NoDatumConve | rsion)             |                   |
|                      | Network Adjustment Transfor                               | Geoid model:             |                         | EGM96 (Global)         |                    |                   |
|                      | Projection<br>Shift Grid                                  |                          |                         |                        |                    |                   |
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Click OK.

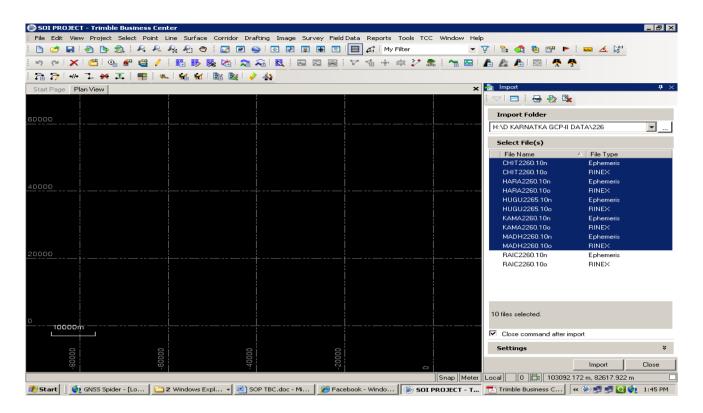
# STEP-3

# **DATA IMPORT**

*"TBC can import data in its raw ( \*dat, \*.T01, \*.T02) as well as in RINEX format "* 1. Menu>File>Import

| ) <b>S</b> O | )I PROJECT - Trimble Business Center                   |         |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       | _ 5      | 21 |
|--------------|--|---------|------|------|-----------|------|-------|-------------|--------|---------|-----|-----|-----|----------|--------|---|------|-------|-------|--------|------|---|-------|------------|-------|----------|----|
|              | Edit View Project Select Point Line Surface Corridor D |         |      |      |           |      | -     | _           |        |         |     | тсс | : w | /indov   |        |   |      |       |       |        |      |   |       |            |       |          |    |
|              | New Project Ctrl-                                      |         |      | 8 🗵  | 1 3       |      |       | <b>1</b> 63 | *   M  | ly Filt | er  |     |     |          | •      | Ţ |      | • <   | 3     | ) 😭    | • •  | 1 | lulu. | <u>Æ</u> , | 30.1  |          |    |
| 0            | Open Project Ctrl+                                     | •       | 2    |      | $\propto$ |      | . 8   | ° 5         | 1 · 🛊  | - 44    | i 🌮 | 1   | 2   | <b>*</b> |        |   | b /  | 2 🖍   |       | 3   4  | *    | 2 |       |            |       |          |    |
|              | New Trimble Survey Project (*.tspx)                    |         |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
|              | Open Trimble Survey Project (*.tspx)                   |         |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
|              | Close Project  | - 1     |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
|              | Save Project Ctrl-                                     | -s      |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
|              | Save Project As  |         |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
| Ľ,           | Save Project As Template                               |         |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
| ۲            | Archive Project  |         |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
| Ð            | Import   |         |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
| <b>b</b>     | Export   |         |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
| C2           | Convert TGO Project                                    |         |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
|              | Internet Download                                      |         |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
| Ð            | Import Format Editor                                   |         |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
| Þ            | Export Format Editor                                   |         |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
| ۹.           | Page Setup   |         |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
| ø            | Print Preview  |         |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
| 8            | Print Ctrl-  | -P      |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
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| ×            | Exit   |         |      |      |           |      |       |             |        |         |     |     |     |          |        |   |      |       |       |        |      |   |       |            |       |          |    |
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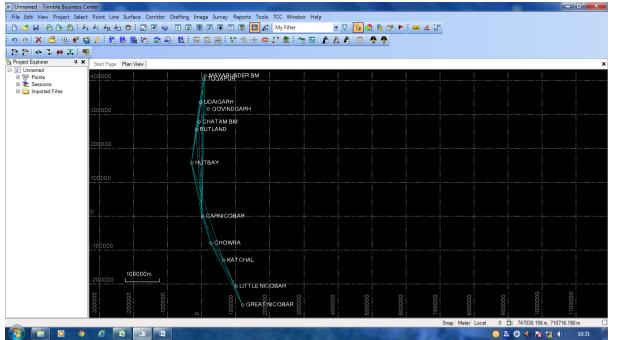
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"Here we can edit the point id & instrument height if required and details regarding the field observation can be checked." THEN CLICK OK.



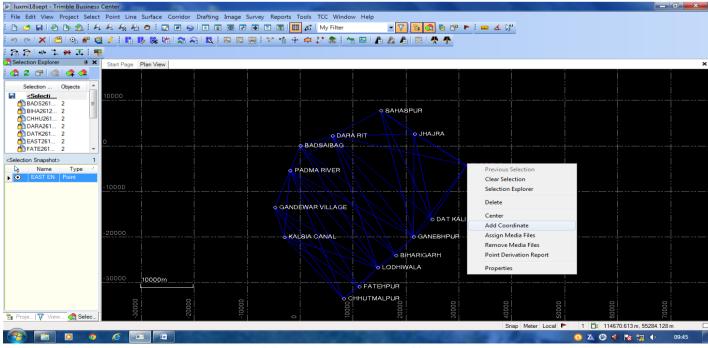
(After the raw data files are imported, the plan view shows all potential baselines (unprocessed base lines) in green color in the survey network. Because the data is raw static data, the baselines must still be processed.)

# **STEP-4**

#### **PROCESSING OF BASELINE**

#### 1. Click Add co-ordinate button

*Note: "It can be done also by selecting the point and then "right click>Add-coordinate" command"* 



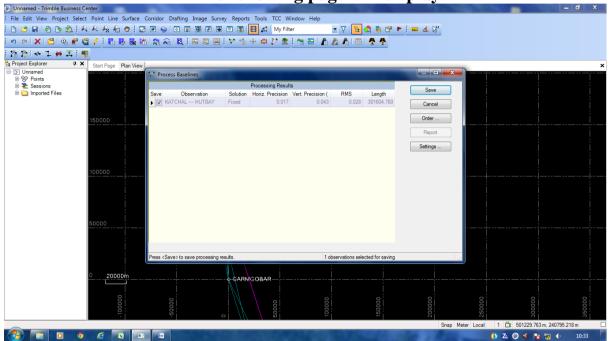
Add the known coordinates

#### Select Co-ordinate Type → Global

Key in your "Latitude, Longitude & Height" and assign it as Control Quality.

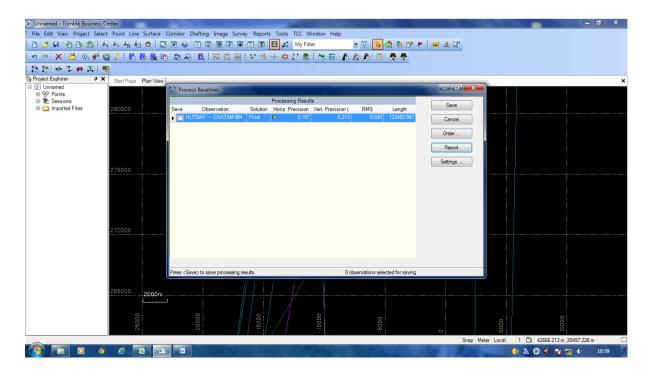
#### Click 🗲 Ok

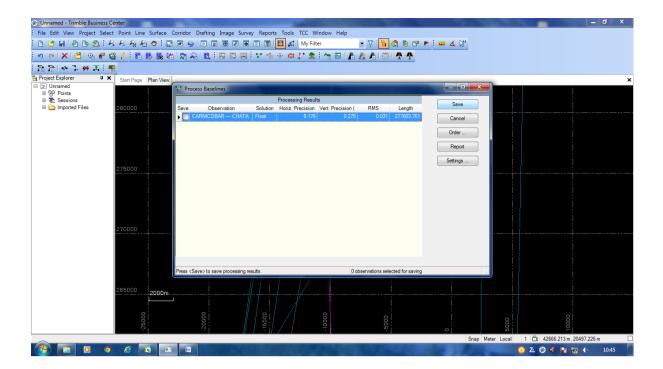
2. Menu>Survey>Processing Baselines



# The following page will display.

# Click Save. Go to next line

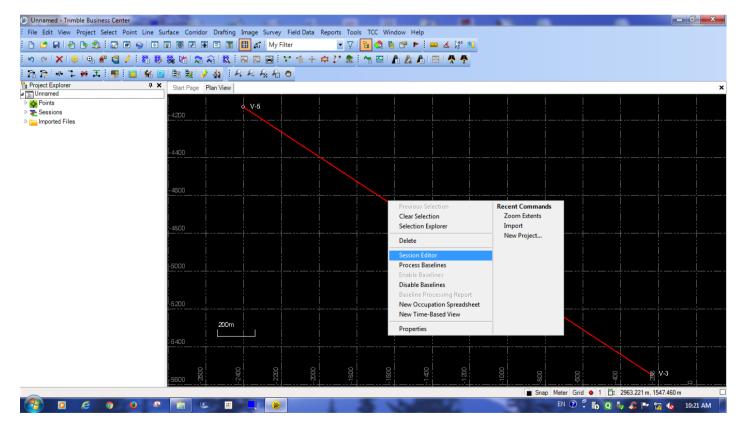




If the solution is fixed and there is not any flag symbol on the baseline save the line, otherwise rectify it with the help of elevation mask and session editor.

NOTE: The blue potential vector showed that the unprocessed base line is processed now.

To open session editor >select baseline>right click the selected baseline>click on session editor

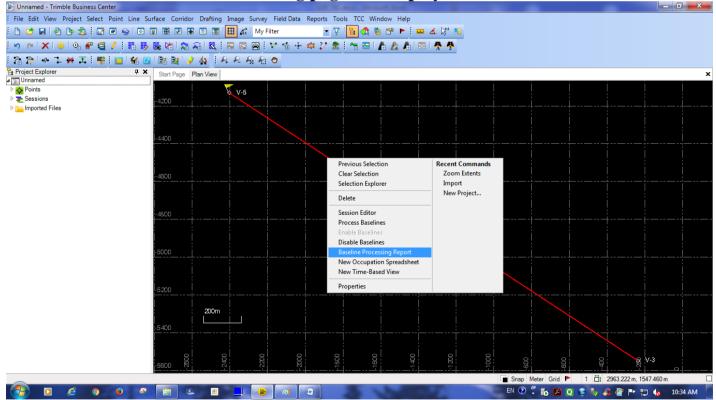


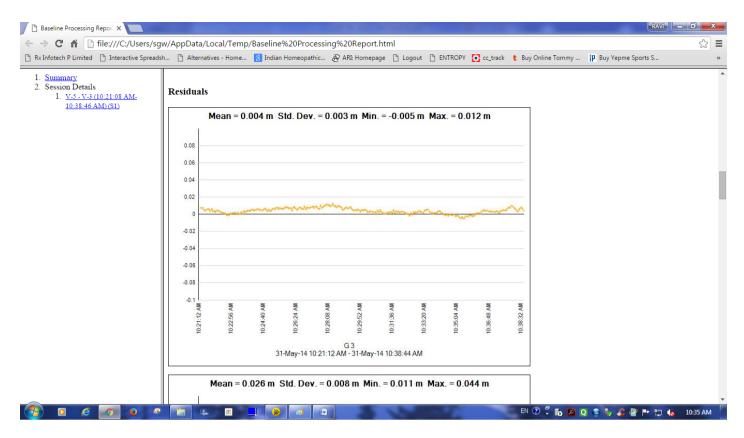
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Here ,satellite for complete duration of observation or part of it can be disabled

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To chose which satellite or part of it to be disabled> select baseline>right click the selected baseline> click on baseline processing report





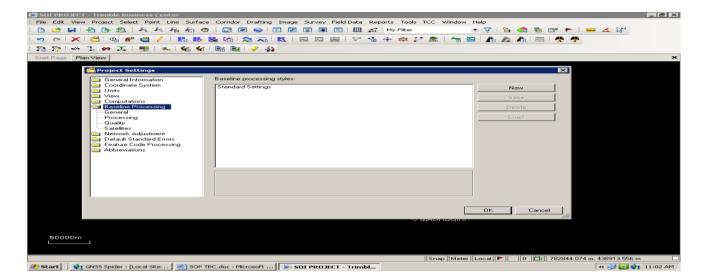
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The baseline processing report can be opened in web view or tab view >Reports(in main menu)>Report options> Baseline processing report

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| Imported Files                              |   |                     | Coordinate System Comparison   |                                |                                       |
|   |   |                     | Corridor Definition Report   |                                |                                       |
|   |   |                     | Corridor Earthwork Report<br>Earthwork Report  |                                | =                                     |
|   | -4400   |                     | Feature Code Processing Report   |                                | · · · · · · · · · · · · · · · · · · · |
|   |   |                     | GNSS Loop Closure Results  |                                |                                       |
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|   |   |                     | Materials and Site Improvements Repo   | rt                             |                                       |
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|   |   |                     | Detailed report about baseline process   | ing.                           |                                       |
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|   |   |                     | Save intermediate data:  | Yes                            | E                                     |
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NOTE: The blue potential vector showed that the unprocessed base line is processed now.

\*Select types of ephemeries through which you want to process ,e.g. broadcast and precise.

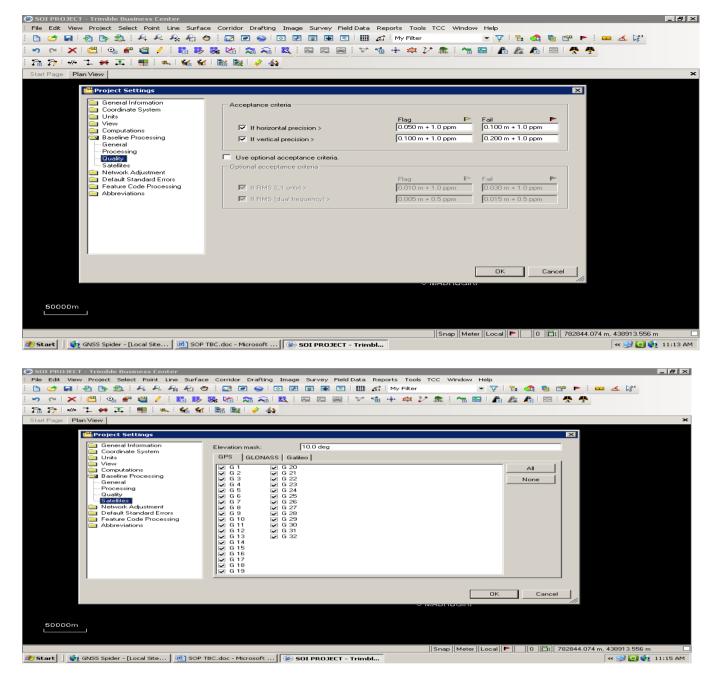


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| Coordinate System                       | Auto start processing:                           | Yes   |              |
| Ciew                                    | Store continuous as trajectory:                  | Yes   |              |
| Computations     Baseline Processing    | Event interpolation type:                        | Linear  |              |
| General                                 | Event interpolation points:                      | 2   |              |
| Processing                              | Start automatic ID numbering:                    | AUT00001                                      |              |
| Guality                                 | Antenna model:                                   | Automatic                                     |              |
| Network Adjustment                      | Ephemeris type:                                  | Automatic                                     |              |
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Precise Ephemeris can be used here if available.

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| Coordinate System                                     | Solution type:   | Fixed  |                  |
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| Computations  | Generate residuals:  | Yes  |                  |
| General   | Processing interval:   | Use all data   |                  |
| - Processing<br>- Quality                             |  |  |                  |
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| Network Adjustment     Default Standard Errors        |  |  |                  |
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|   | Choose a frequency type to process, "L1 only" forces the<br>forces the processor to use L1 and L2 data only, "Multiple | processor to use L1 data only. "Dual Frequency (L1, L2)"<br>Frequencies" allows the processor to use all available |                  |
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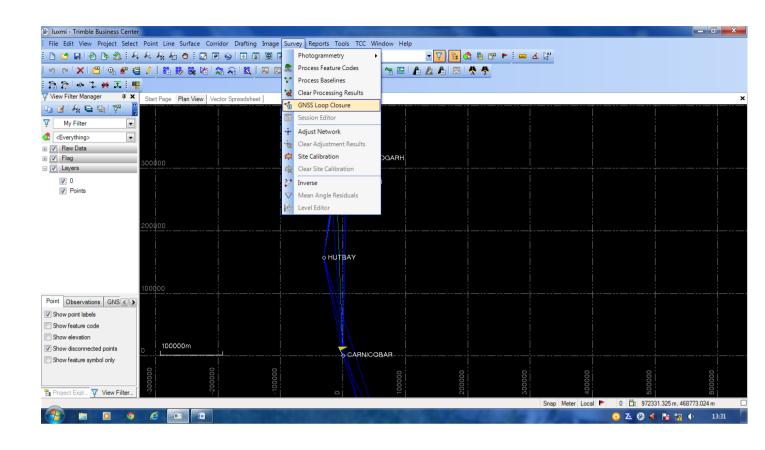


Elevation mask can be changed here, if required.

# **Loop Closure**

Now before going for the adjustment the loop closure must be checked. The Loop Closure Results report is a useful way to find large blunders in the data set, Such as errors with antenna heights, one point with different name or different point with same name.**However,loop closure can only be checked in case of close figure For this select the command** 

Menu> Survey> GNSS loop closure



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| ummary                  | Project Information   | Coordinate                      | System            |                  |   |
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|                         | Reference number:   | Vertical data                   | um:               |                  |   |
|                         | Description:  |                                 |                   |                  |   |
|                         | GNSS  | Loop Closure Results            |                   |                  |   |
|                         | GNSS  | Loop Closure Results<br>Summary |                   |                  |   |
|                         |   | •                               |                   |                  |   |
|                         | Legs in loop: 3   | •                               |                   |                  |   |
|                         | Legs in loop: 3<br>Number of Loops: 54  | •                               |                   |                  |   |
|                         | Legs in loop: 3<br>Number of Loops: 54<br>Number Passed: 54                     | •                               |                   |                  |   |
|                         | Legs in loop: 3<br>Number of Loops: 54  | Summary                         | Alfonia           | AVort            |   |
|                         | Legs in loop: 3<br>Number of Loops: 54<br>Number Passed: 54                     | Summary<br>Length A3D           | ∆Horiz<br>(Meter) | ΔVert<br>(Meter) |   |
|                         | Legs in loop: 3<br>Number of Loops: 54<br>Number Passed: 54<br>Number Failed: 0 | Summary                         | ΔHoriz<br>(Meter) | ΔVert<br>(Meter) | 1 |
|                         | Legs in loop: 3<br>Number of Loops: 54<br>Number Passed: 54                     | Summary<br>Length A3D           |                   |                  | 1 |

# **STEP-5**

# **NETWORK ADJUSTMENT**

"Once all baselines in the control network have been processed and reviewed, you can adjust your survey network"

#### SURVEY> ADJUST NETWORK

Note:

If the elevation (MSL height) of a station (Bench Mark) is available, then the adjusted vertical control can be obtained from the network up to sub metre level accuracy.

Click Add co-ordinate button

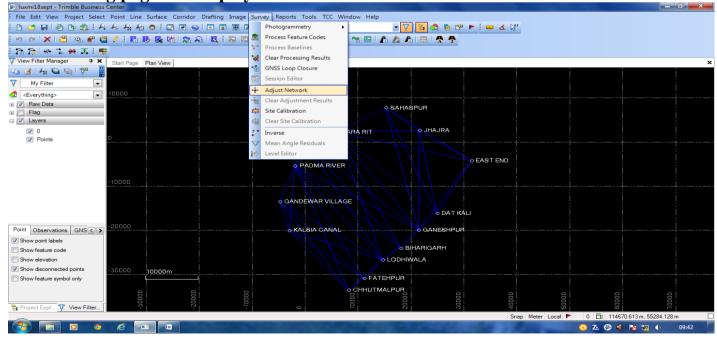
*Note: "It can be done by selecting the point and then "right click>Add-coordinate" command"* 

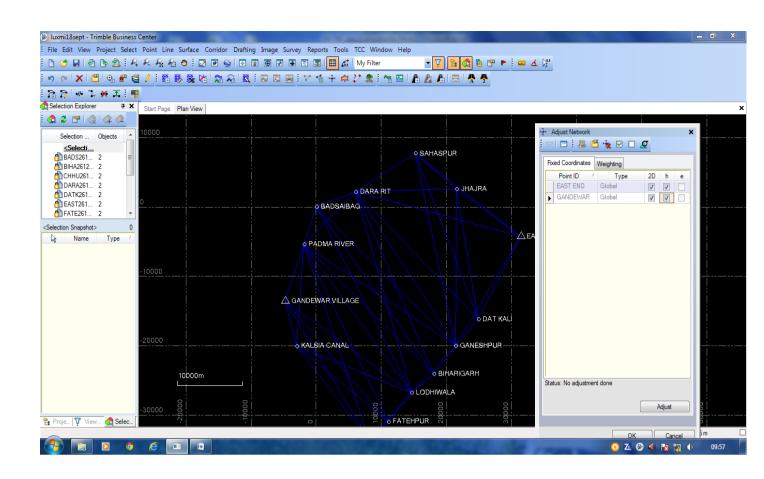
Select Co-ordinate Type → Gird

Key in your "MSL Height" and assign it as Control Quality.

### Click 🗲 Ok

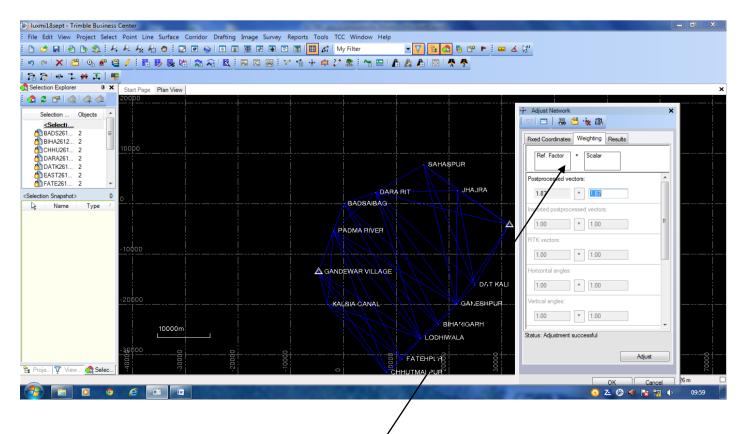
Select the following command Menu>Survey>Adjust Network The following page will display.





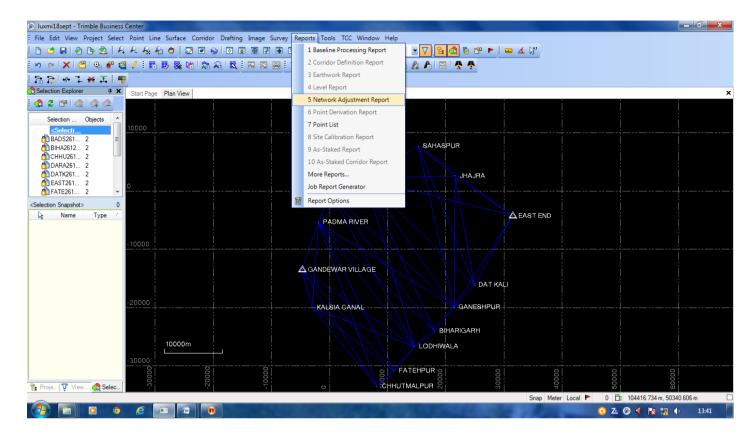
Check on → "2D & h" box if MSL Height to be fixed then check on "2D & e" box Click → Adjust

NOW Click → Weighting This step is required if the value shown below the Postprocessed vector (1.87 in this case) is not coming near about 1



Make a click on \* in Post processed vectors tab:

Now again "Adjust" the data Note: For Adjustment Report



# Point to be checked in Network Adjustment Report

Network Reference Factor must be one or near to one Chi Square Test must be passed Horizontal and vertical error must be in reasonable limit All vector must be in black colour under Adjusted GNSS Observations

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| <u>Adjustment Settings</u>           | Network Adjustment Report  | ^                 |
| <u>Adjustment Statistics</u>         | Adjustment Settings  |                   |
| <u>Control Point Constraints</u>     | Set-Up Errors  |                   |
| <u>Adjusted Grid Coordinates</u>     | GNSS<br>Error in Height of Antenna: 0.000 m  |                   |
| <u>Adjusted Geodetic Coordinates</u> | Centering Error: 0.000 m   |                   |
| Adjusted ECEF Coordinates            | Covariance Display<br>Horizontal:<br>Propagated Linear Error [E]: U.S.   |                   |
| Error Ellipse Components             | Constant Term [C]: 0.000 m   |                   |
| <u>Adjusted GPS Observations</u>     | Scale on Linear Error [S]:       1.960         Three-Dimensional         Propagated Linear Error [E]:       U.S. |                   |
| <u>Covariance Terms</u>              | Constant Term [C]:       0.000 m         Scale on Linear Error [S]:       1.960                                  |                   |
|                                      | Adjustment Statistics  |                   |
|                                      | Number of Iterations for Successful Adjustment: 2  |                   |
|                                      | Network Reference Factor: 1.00   |                   |
|                                      | Chi Square Test (95%): Passed<br>Precision Confidence Level: 95%   | ~                 |
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| Adjustment Settings           |                               |                  |                  |                   |                         |           |
|-------------------------------|-------------------------------|------------------|------------------|-------------------|-------------------------|-----------|
| Adjustment Statistics         | Adjusted Geodetic Coordinates |                  |                  |                   |                         |           |
| Control Point Constraints     | Point ID                      | Latitude         | Longitude        | Height<br>(Meter) | Height Error<br>(Meter) | Constrain |
| Control Fourt Constraints     | BADSAIBAG                     | N30°19'27.03318" | E77°38'50.39976" | 379.085           | 0.051                   |           |
| Adjusted Grid Coordinates     | BIHARIGARH                    | N30°06'24.31225" | E77°50'04.38991" | 272.743           | 0.054                   |           |
|                               | CHHUTMALPUR                   | N30°01'15.80241" | E77°43'54.93407" | 243.841           | 0.050                   |           |
| Adjusted Geodetic Coordinates | DARA RIT                      | N30°20'37.75905" | E77°42'38.12520" | 624.762           | 0.045                   |           |
|                               | DATKALI                       | N30°10'40.31027" | E77°54'20.48698" | 423.740           | 0.057                   |           |
| Adjusted ECEF Coordinates     | EAST END                      | N30°17'06.92861" | E77°58'26.04106" | 555.861           | ?                       | LLh       |
| Aujusteu ECEF Coordinates     | FATEHPUR                      | N30°02'41.62938" | E77°45'44.42007" | 249.778           | 0.083                   |           |
| Error Ellipse Components      | GANDEWAR VILLAGE              | N30°12'06.51835" | E77°35'50.75162" | 258.795           | ?                       | LLh       |
|                               | GANESHPUR                     | N30°08'36.85398" | E77°52'10.91034" | 332.216           | 0.040                   |           |
| Adjusted GPS Observations     | JHAJRA                        | N30°20'50.33267" | E77°52'17.08659" | 472.385           | 0.059                   |           |
|                               | KALSIA CANAL                  | N30°08'35.90592" | E77°36'57.67944" | 250.337           | 0.085                   |           |
| Covariance Terms              | LODHIWALA                     | N30°04'57.07964" | E77°47'56.96987" | 252.244           | 0.039                   |           |
| Covariance rerms              | PADMA RIVER                   | N30°16'31.35878" | E77°37'38.39688" | 294.254           | 0.036                   |           |
|                               | SAHASPUR                      | N30°23'36.64796" | E77°48'19.98528" | 432.386           | 0.054                   |           |

| <u>Adjustment Statistics</u> <u>Control Point Constraints</u> | Adjusted ECEF Coordinates |              |                    |              |                    |              |                    |                     |            |
|---|---------------------------|--------------|--------------------|--------------|--------------------|--------------|--------------------|---------------------|------------|
| <u>Adjusted Grid Coordinates</u>                              | Point ID                  | X<br>(Meter) | X Error<br>(Meter) | Y<br>(Meter) | Y Error<br>(Meter) | Z<br>(Meter) | Z Error<br>(Meter) | 3D Error<br>(Meter) | Constraint |
|   | BADSAIBAG                 | 1178858.381  | 0.012              | 5382955.286  | 0.043              | 3201636.122  | 0.026              | 0.052               |            |
| <u>Adjusted Geodetic Coordinates</u>                          | BIHARIGARH                | 1163799.716  | 0.012              | 5398546.663  | 0.046              | 3180753.548  | 0.027              | 0.055               |            |
|   | CHHUTMALPUR               | 1174473.538  | 0.013              | 5401079.597  | 0.042              | 3172516.942  | 0.027              | 0.051               |            |
| <u>Adjusted ECEF Coordinates</u>                              | DARA RIT                  | 1172725.636  | 0.010              | 5383385.880  | 0.038              | 3203640.107  | 0.024              | 0.046               |            |
| Error Ellipse Components                                      | DAT KALI                  | 1156293.960  | 0.012              | 5396244.379  | 0.048              | 3187646.769  | 0.030              | 0.058               |            |
|   | EAST END                  | 1148643.760  | ?                  | 5391865.580  | ?                  | 3198000.239  | ?                  | ?                   | LLh        |
| <ul> <li>Adjusted GPS Observations</li> </ul>                 | FATEHPUR                  | 1171327.166  | 0.023              | 5400414.549  | 0.070              | 3174807.996  | 0.042              | 0.084               |            |
| Aujusted OF 5 Observations                                    | GANDEWAR VILLAGE          | 1184992.332  | ?                  | 5388502.191  | ?                  | 3189858.510  | ?                  | ?                   | LLh        |
|   | GANESHPUR                 | 1160068.441  | 0.009              | 5397307.051  | 0.034              | 3184313.651  | 0.021              | 0.041               |            |
| <u>Covariance Terms</u>                                       | JHAJRA                    | 1157541.764  | 0.013              | 5386336.545  | 0.049              | 3203897.297  | 0.032              | 0.060               |            |
|   | KALSIA CANAL              | 1183941.357  | 0.024              | 5392063.162  | 0.069              | 3184247.287  | 0.048              | 0.087               |            |
|   | LODHIWALA                 | 1167415.363  | 0.009              | 5399125.901  | 0.033              | 3178419.134  | 0.020              | 0.039               |            |
|   | PADMA RIVER               | 1181306.535  | 0.009              | 5385137.964  | 0.031              | 3196922.376  | 0.019              | 0.037               |            |
|   | SAHASPUR                  | 1163178.305  | 0.012              | 5382437.522  | 0.045              | 3208296.113  | 0.029              | 0.055               |            |

# Disclaimer

This SOP is made assuming that user has some previous knowledge of GPS data processing ,However for user with no previous knowledge of GPS data processing ,hands on training is recommended.

# SOP for GNSS Observation in Order to Determine Latitude, Longitude & Ellipsoidal Height and subsequently use of Geoid Model for National <u>Hydrology Project.</u>

The coordinates obtained from GPS/GNSS observations are burdened with many errors like Satellite Clock and orbit error, Ionospheric delay and Topospheric delay, Receiver Noise, Multipath and Receiver Clock error. Due the above errors the coordinates obtained are inaccurate and needs to be corrected before use.

To minimize the effect of these errors the GPS/GNSS data of observation points needs to be processed with reference to some known reference stations whose coordinates are accurately known to us.

The reference stations are of two types

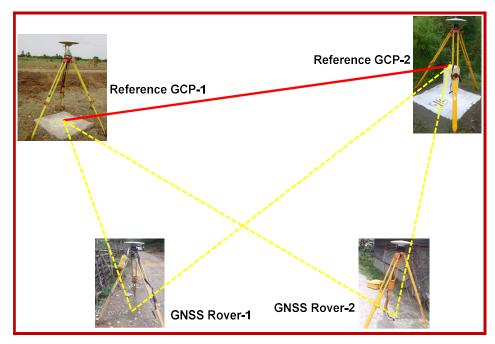
- 1. CORS Network established by SOI: Active Network of Reference Stations
- 2. SOI GCPs: Passive Network of Reference Stations

# 1. CORS Network established by SOI: Active Network of Reference Stations

- Continuously Operating Reference Stations CORS are geodetic quality GNSS receivers and antennas that are permanently installed at a Reference Station (RS) having very accurately predetermined coordinates.
- These Reference Stations collect GNSS data continuously, and transmit data via Internet to a central server (Control & Processing Centre).
- The incoming data is processed at the server to generate corrections which are made available to users over the Internet in real-time in order to get the accurate coordinates.
- To get accurate coordinates using the CORS network is known as Network Real Time Kinematic (NRTK) survey technique.
- To avail the facility of NRTK survey users needs to have a RTK enabled GNSS receiver with internet connectivity.
- Different brand receivers are available in the market. The Standard Operating Procedure (SOP) to carry out NRTK survey is different for different brand receivers.
- At present SOI is using **Trimble R8s** GNSS receiver for NRTK survey. The SOP to carry out NRTK survey using **Trimble R8s GNSS receiver given in Annexure 'A'**.

#### 2. SOI GCPs: Passive Network of Reference Stations

- The states where CORS network is not available, the SOI GCPs can be used as reference stations to get the accurate latitude longitude and ellipsoidal height of the survey points.
- The SOI has established Ground Control Point (GCP) Library of about 2500 Ground Control Points in the entire country and derived their coordinates (Latitude, Longitude and Ellipsoidal Height) with high accuracy. These GCPs define the Horizontal datum of the country and can be used for various surveying, mapping and developmental activities. These GCPs has cement concrete structure/Monumentation and can be located on the ground by their description which is available with SOI. These GCPs are passive reference stations.
- To get the accurate coordinates of survey points for any surveying and mapping activity the GPS/GNSS observation of survey points needs to be carried out for 1 to 2 hours with reference to SOI GCPs in static and relative/differential mode. The GPS/GNSS data thus collected needs to be processed with reference to SOI GCPs in order to derive the accurate coordinates (Latitude, Longitude and Ellipsoidal Height) of new survey points.
- The coordinates of reference GCPs which is required during the post processing can be obtained from SOI as per departmental policy.
- In this process at least two Observers with two GNSS receivers needs to occupy the Reference GCPs falling in the area of work and one or more observers needs to occupy the new survey points with 1 to 2 hours common observation duration.



- This technique is known as static survey technique and require the at least three GNSS receivers. More receivers will increase the progress of the work.
- The static survey requires:
  - 0 1 to 2 hours GNSS Data collection using GNSS receiver

- GNSS data downloading from the receiver to a computer having GNSS data processing software and finally
- GNSS data Processing using software
- The SOP for GNSS data collection in static mode using a **Trimble R8s GNSS** receiver and downloading to a computer is given in **Annexure 'B'**.
- The SOP for GNSS data processing using Trimble Business Center (TBC) software is given in Annexure 'C'.
- The output of NRTK as well as static survey is accurate Latitude, Longitude and ellipsoidal heights.
- In order to get Orthometric Height of survey points, the Latitude, Longitude and Ellipsoidal heights of survey points can be supplied to SOI. The SOI use the Geoid model and convert the ellipsoidal heights into Orthometric Heights.
- The SOPs as mentioned above are given in Annexure 'A', 'B' and 'C'.